

Amendments To The Claims:

Claim 1 (*Currently Amended*) A fork-lift truck comprising:

 a mast,

 a load carrying fork,

 a pair of actuation drives, one being a lifting and lowering drive, and one being an inclination drive,

 an analog sensor, and

 a control device, wherein:

 the load-carrying fork is engaged to and supported by the mast and is adjustable in height by the lifting and lowering drive,

 the inclined position of the load-carrying fork is adjustable relative to a horizontal axis by the inclination drive, and

 the control device is in electrical communication with and regulates the actuation of the lifting and lowering drive and is in separate electrical communication with and separately regulates the inclination drive,

 said regulation comprises utilizing the analog sensor to detect the inclined position of the load-carrying fork relative to the horizontal axis and correspondingly emitting an inclination signal to the control device, the control device in turn processes the inclination signal and induces a coordinated actuation of both ~~at least one~~ of the actuation drives such that they cause the load-carrying fork to be automatically moved to a predetermined position.

Claim 2 *(Previously Presented)* The fork-lift truck of claim 1, characterized in that the control device induces the load-carrying fork to be automatically moved to a horizontal position.

Claim 3 *(Previously Presented)* The fork-lift truck as claimed in claim 1, characterized in that the control device induces the inclination drive to move the load-carrying fork colinear with the horizontal axis when the lifting and lowering drive are induced by the control device to be actuated.

Claim 4 *(Previously Presented)* The fork-lift truck as claimed in claim 1 further comprising an engine and an onboard computer, the engine controlling the speed of the fork-lift truck, the onboard computer in controlling communication with the engine such that it limits the traveling speed and cornering speed of the fork-lift truck in conformity with stability criteria, the inclination signal is also received by the onboard computer for a modification of the maximum traveling speed of the fork-lift truck in dependence on the inclination signal.

Claim 5 *(Previously Presented)* The fork-lift truck of claim 1, characterized in that the control device measures the inclined position of the load-carrying fork relative to the horizontal axis.

Claim 6 *(Previously Presented)* The fork-lift truck of claim 1, characterized in that the control device induces the load-carrying fork to be automatically moved to a pre-determined height.